

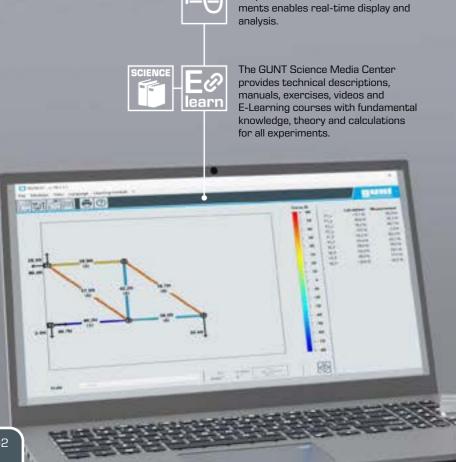


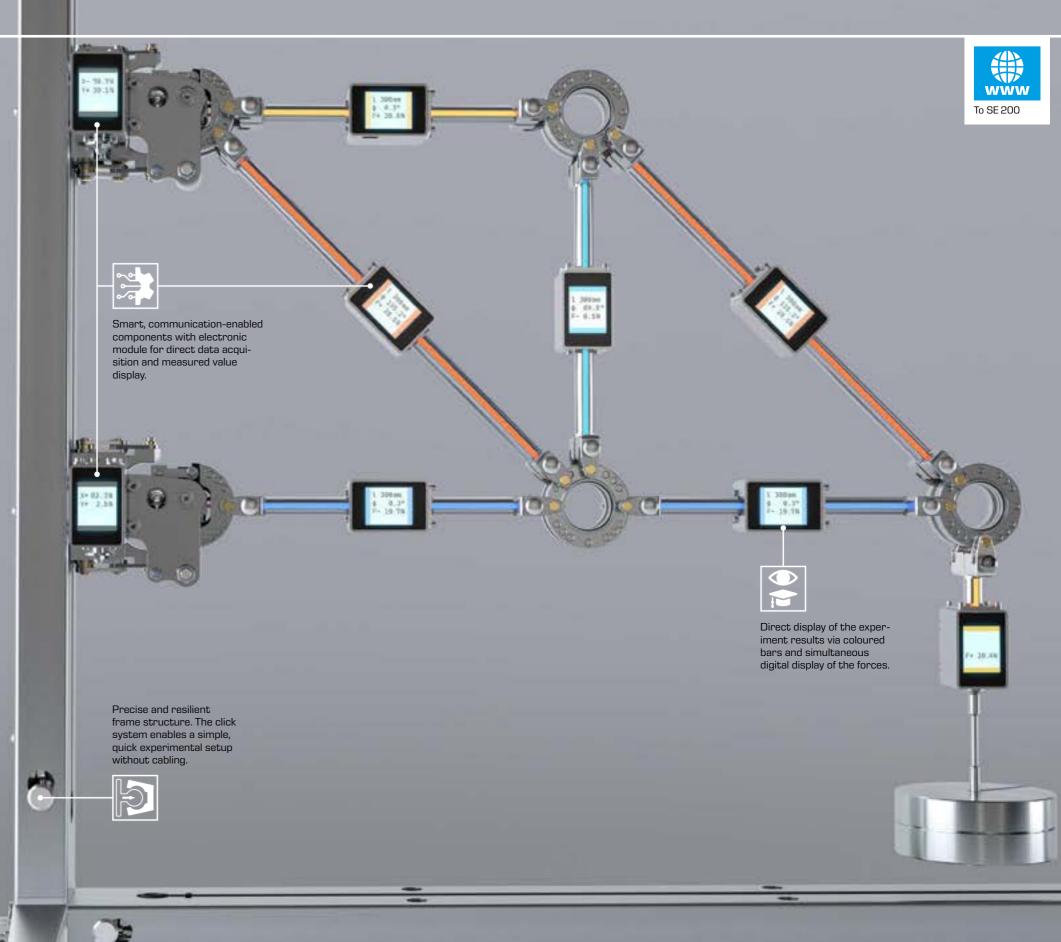
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Custom GUNT software with content adapted to the individual experi-









# Didactics and methodology

### Experiments using all the senses – for an in-depth learning experience

Develop the fundamentals of engineering mechanics according to textbook and curriculum in experiments

#### Vhat:

- static systems in equilibrium of forces
- trusses: internal reaction and support reaction under external loads
- elastic reactions under external loads
- analysis of typical elements from civil engineering: beams, bridges
- familiarisation with stability problems

Familiarisation with digital concepts and methods of measurement technology and data processing simultaneously

#### Hov

- implement theoretical teaching topics in experiments by planning series of experiments and setting up your own experiments
- technically realise terms such as fixation or articulated support
- coloured display of forces, display of the loading as well as automatic topology transmission for direct feedback
- microprocessor-based measurement technology for force and angle, distance, position and identification
- application of Gray codes (reflected binary, RB)
- integration of FEM models, strength verification, etc.



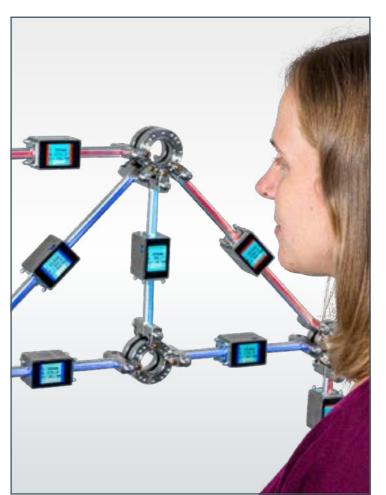
### Haptic experience

- promotes the comprehension and internalisation of learning content through the sense of touch
- manual work and skill in setting up experiments
- no disruptive cabling of the individual elements
- sturdy components with click system, quick and easy to assemble



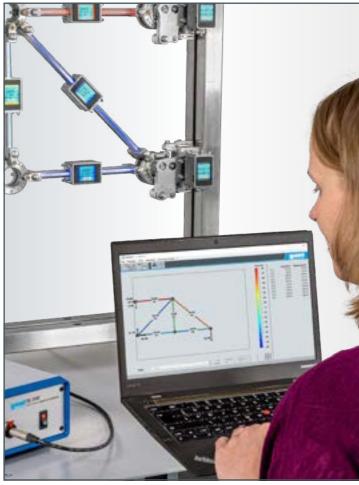
### Experimental learning

- promotes self-directed learning and effective teamwork
- accessories of the series can be combined in a modular way for setup and extension of the experiments
- possibility to create your own experiments with many variations



### Visual comprehension

- promotes abstraction skills
- visual representation of experimental processes that are otherwise invisible and can only be understood through calculation



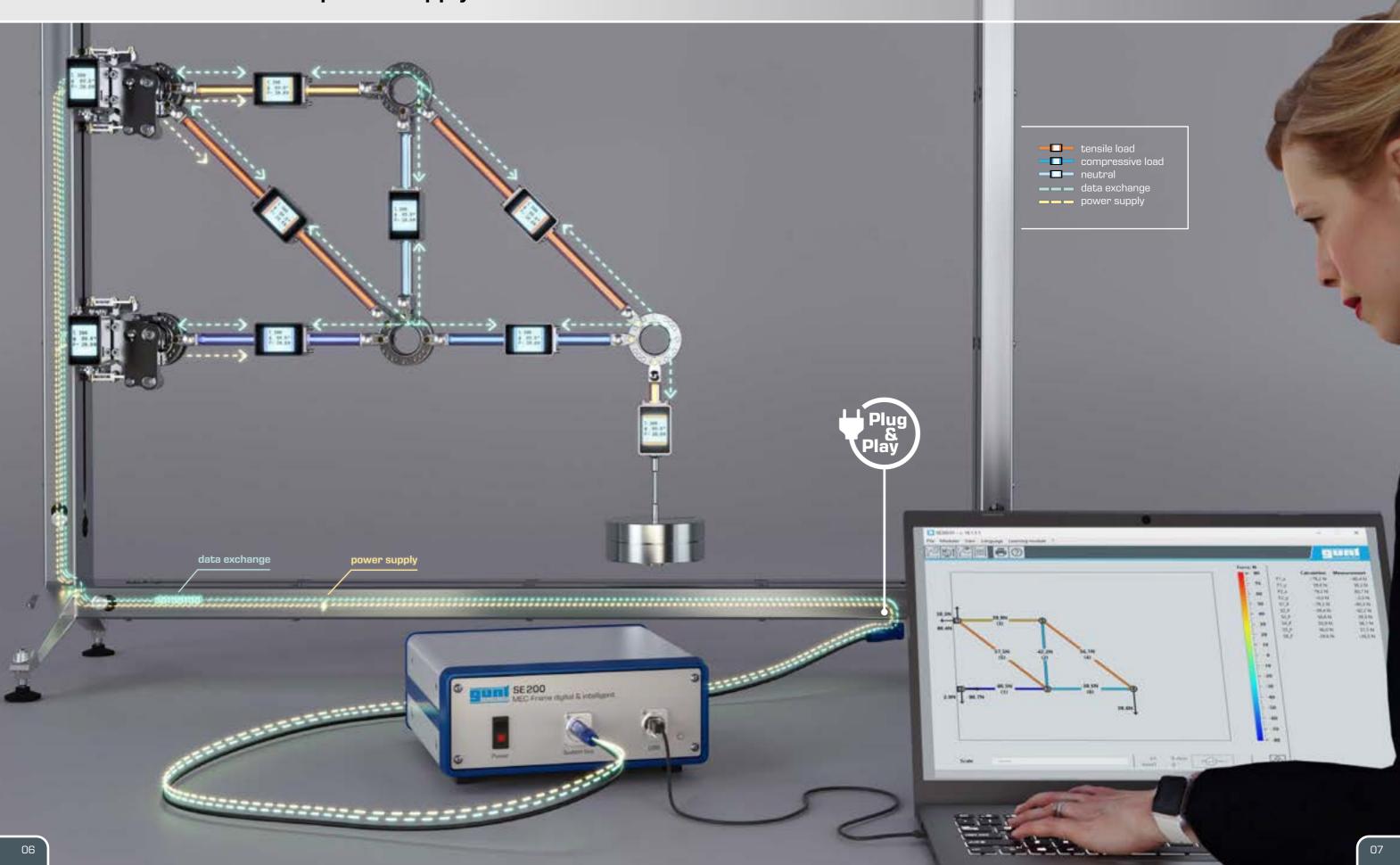
# Logical thinking

- promotes the recognition of interrelationships through the transmission of topology
- analysis of measurement results and estimation of errors





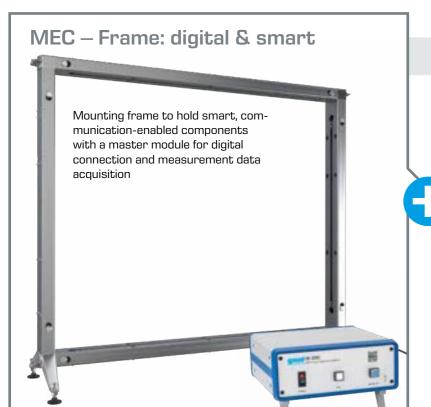




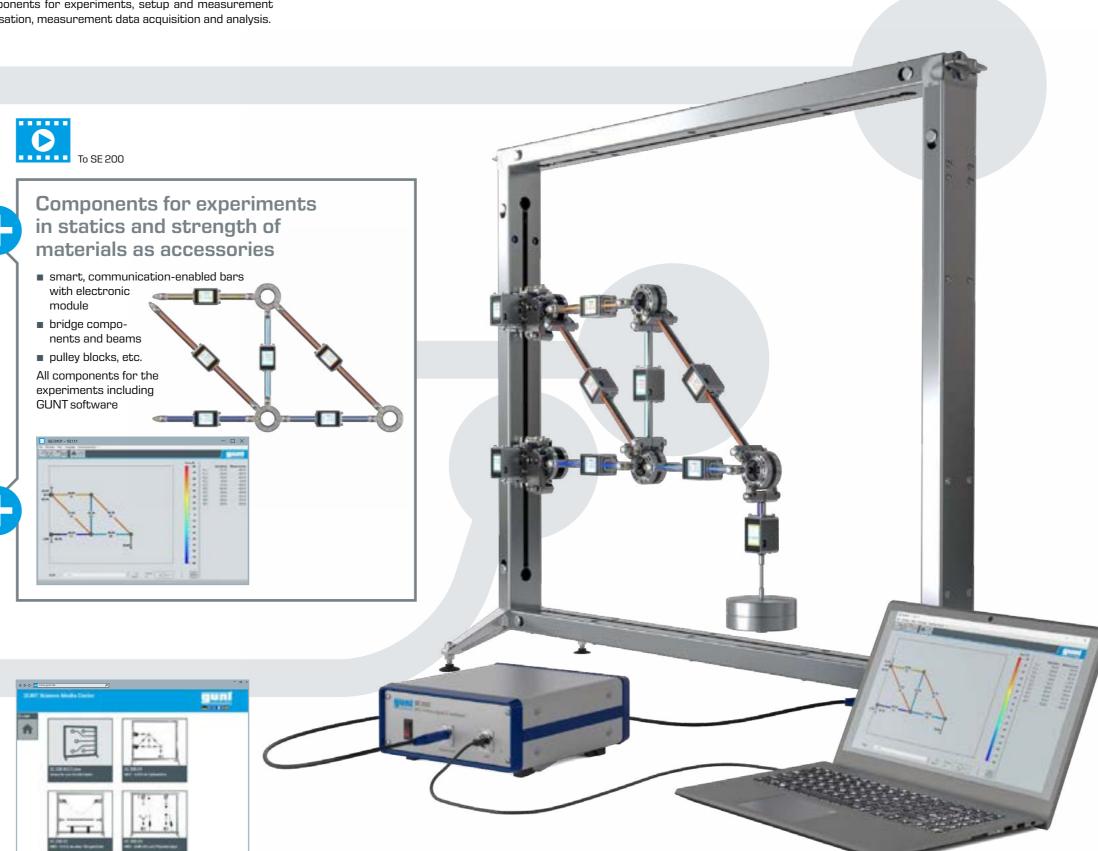


# Structure of the MEC Line

Full experimental setups are created from the mounting frame and the components for experiments, setup and measurement technology. The experiments are accompanied by software for real-time visualisation, measurement data acquisition and analysis.







Access to the GUNT Science Media Center



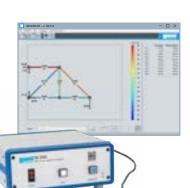
# Smart, communication-enabled components for the setup and measurement technology

## Components for the setup



# Mounting frame

- base element for setting up versatile experiments
- click system for easy setup and reconfiguration, no tools required
- stainless steel hollow sections with integrated electrical cable
- defined snap-in points for exact topology determination and transmission



- Master module and software
- master module detects all data from the electronic modules and transmits it to the GUNT software via USB
- automatic identification of the smart, communication-enabled components including position and alignment
- master module connected via Plug&Play and only 1 power **BUS line**



- fixed support for connecting smart, communication-enabled components via click
- horizontal or vertical installation at different positions in the mounting frame
- automatic detection of the installation position and dynamic adjustment in the GUNT

#### Electronic module

- equipped with planar beam load cells for direct force measurement in x, y direction
- integrated acceleration sensor for angle measurement for correct display of the geometry



- tool-free setup and reconfiguration of various trusses without cabling
- force displayed as a measured value and as coloured illumination directly on the bar
- bars with articulated connection to node disks; loading only on compression or tension

#### Electronic module

- equipped with planar beam load cell for direct force measurement in the x direction
- communication in both bar directions to determine topology
- integrated acceleration sensor for angle measurement for correct display of the geometry

# Components for measurement technology



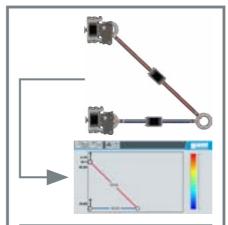
### Line load

- generation of weight forces through concentrated load
- generation of line loads by combining several load elements
- electronic module with Gray code reader for position detection and transmission to the GUNT software



#### Vertical load

- various weights included in delivery
- visual representation of the force as coloured illumination
- electronic module contains Planar Beam load cell for direct force measurement; transfer of position using topology



# Topology

- real-time transmission of the topology to the geometry display in the GUNT software
- exact visualisation of the experiments during setup
- special algorithm for topology transmission, developed by GUNT



## Distance measurement

- articulated arm with long reach
- electronic module contains linear potentiometer for detecting paths and an acceleration sensor for detecting the measuring direction

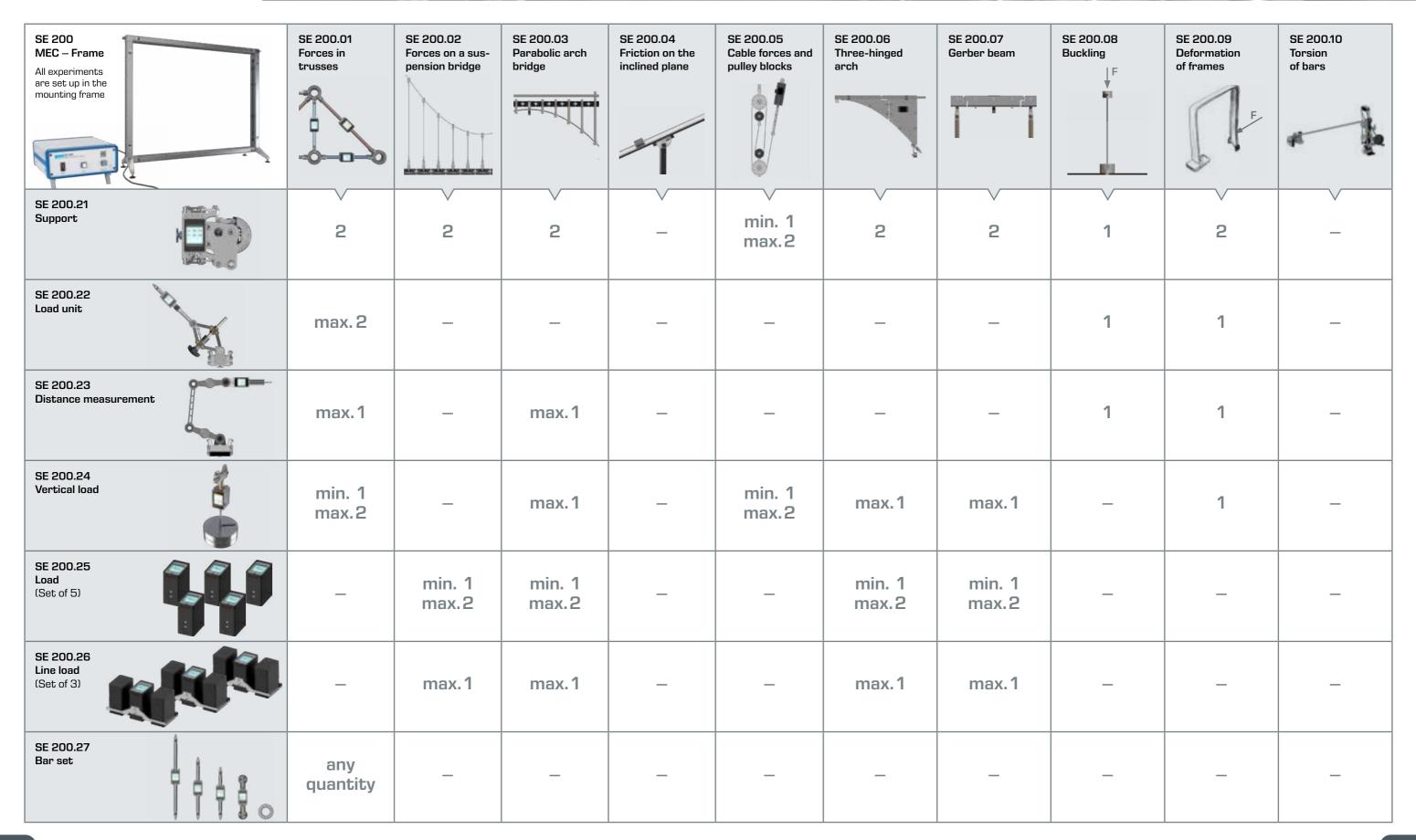


#### Load unit

- stepless generation of tensile and compressive forces in any direction
- visual representation of force
- electronic module contains Planar Beam load cell for direct force measurement and an acceleration sensor to detect the measuring direction



# Accessories







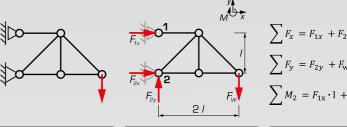
# SE 200.01 MEC – Forces in trusses

- smart, communication-enabled bars with electronic modules for data acquisition and measured value display
- setup of various trusses without cabling
- automatic identification and assignment of the bars in the **GUNT** software
- measured values and coloured display of the force directly
- calculated displacement of the truss can be magnified in the

# Learning objectives measurement of the bar forces in a statically determinate and statically indeterminate plane dependence of bar forces on the external force comparison of measurement results with mathematical solution methods basic principle: using strain gauge technology to measure

#### Exercises

- Setup of any truss with at least 6 bars and 1 load
  - exact recording of the geometry with real-time transmission to the **GUNT** software
- measured values displayed directly on the bar, can be hidden if required
- Calculation of external forces: loading by load, reaction of the supports

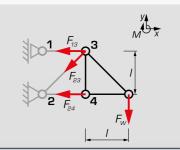


constructed truss

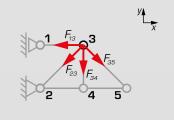
Simplified sketch for the Freeing the support forces

Setting up the equilibrium conditions

Calculation of internal forces: select and apply method of joints or Ritter's method of sections

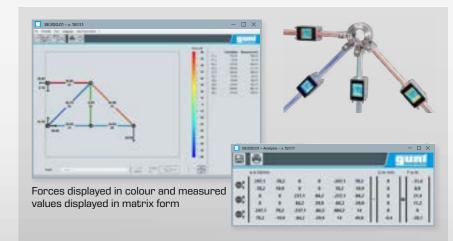


Ritter's method of sections: freeing the bar forces at nodes 3 and 4



Method of joints: freeing the bar forces at node 3

Checking the calculation: comparison of results with measured values and results in the GUNT software



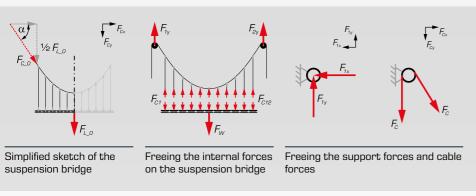




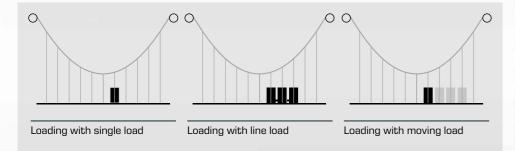
# SE 200.02 MEC – Forces on a suspension bridge

### **Exercises**

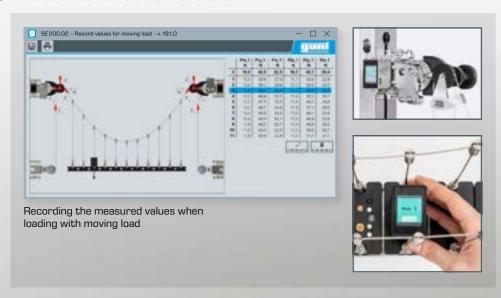
- Setup of a suspension bridge with rigid roadway and no additional loading
  - exact recording of the geometry with real-time transmission to the GUNT software
- measured values displayed directly on the supports, can be hidden if required
- Calculation of external and internal forces without additional loading



Calculation of external and internal forces with additional loading by single load, line load or moving load



Checking the calculation: comparison of results with measured values at load/supports and the results from the GUNT software







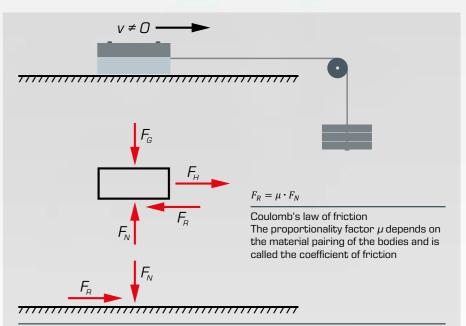
# SE 200.04 MEC – Friction on the inclined plane



### **Exercise**

Setup of an inclined plane on which a friction body is set in motion.

Investigation of the acting forces and measurement of the coefficients for adhesion and friction.



Freeing the forces to determine the coefficient of friction: v velocity,  $F_G$  weight,  $F_R$  force of dynamic friction,  $F_N$  normal force,  $F_H$  external force e.g. tensile force



Two friction bodies: 1x with wheels, 1x without wheels



GUNT software: forces and inclination angles, selection of the friction surface and flywheels



Variable loads for loading the friction body

# Learning objectives

- measurement of the static and dynamic friction coefficient on an inclined plane
  - determination of angular dependence and material dependence
  - measurement of distance travelled and time
  - determination of velocity and acceleration





# SE 200.05 MEC — Cable forces and pulley blocks

### **Exercises**

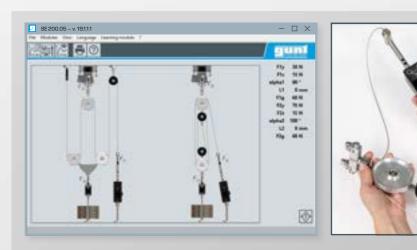
- Setup of a four-cable pulley block with at least one loose and one four laws. one loose and one fixed pulley
  - exact recording of the geometry with realtime transmission to the GUNT software
  - measured values displayed directly on the suspension cables, can be hidden if required



■ smart, communicationenabled suspension cables with electronic sition and measured

Calculation of cable forces and support forces Equilibrium of forces: Equilibrium of forces:  $\sum F_{y} = 0 = 4 \cdot F_{c} - F_{L}$  $\sum_{x} F_{y} = 0 = F_{B} - 2 \cdot F_{C}$ Cable force: Support force: Setting the equilibrium Setting the equilibrium condition and calculacondition and calculation of cable force tion of support force Freeing the load to determine Freeing the support forces the cable forces

Checking the calculation: comparison of results with the measured values on suspension cable/supports and the results from the GUNT software



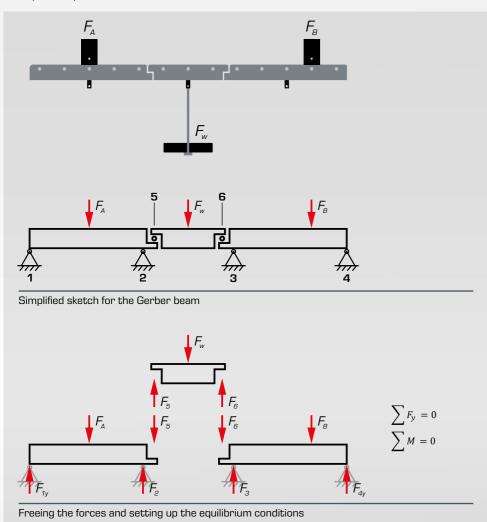




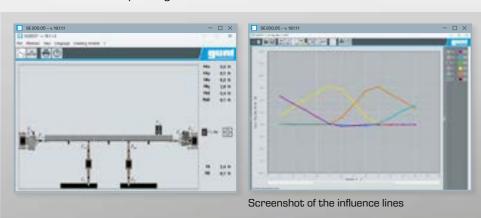
# SE 200.07 MEC - Gerber beam

### **Exercises**

Setup of a bridge consisting of a statically determined Gerber beam with different loads. Development of a simplified sketch for the system. Set up the equilibrium conditions.



Experimental setup with a moving load on the roadway. Evaluation of the corresponding influence lines.



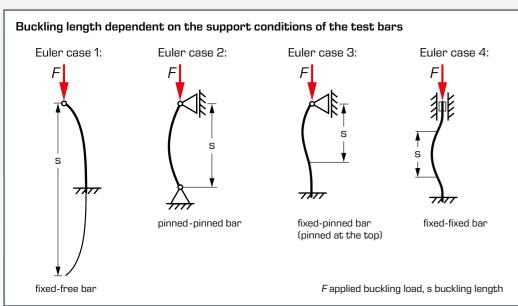


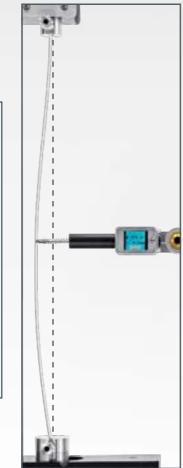




# SE 200.08 MEC – Buckling

- measurement of buckling forces and deflections on test bars for all 4 Euler cases
- high transmission ratio for a wide range of experiments (1:10)
- different types of support for test bars: free, hinged and clamped
- automatic identification and assignment of accessories during setup and while conducting the experiment

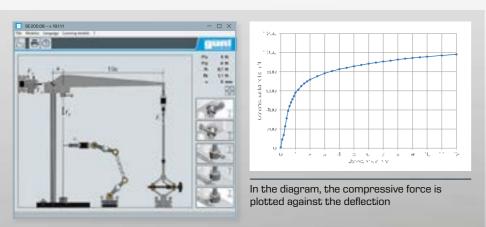




Euler case 3: bar fixed at the top, pinned at the bottom; the buckling of the test bar is measured

# Exercise

The deflection (deformation) of the test bar is measured. A force-deformation diagram is to be created from these measured values and compared with the values from the buckling theory.



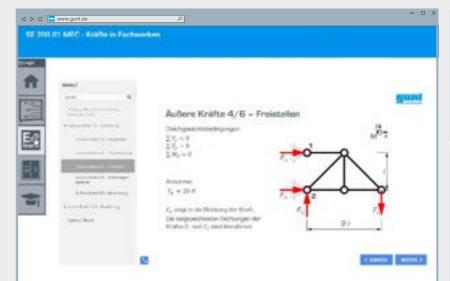




# **GUNT Science Media Center**



# The E-Learning course



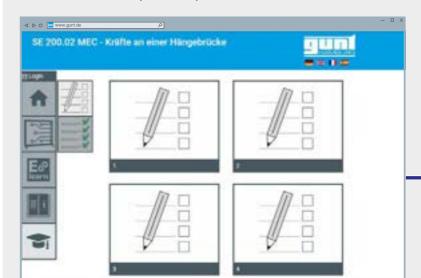
The E-Learning course presents fundamental knowledge and the experiment procedure in detail with engaging animations. Knowledge tests facilitate understanding.

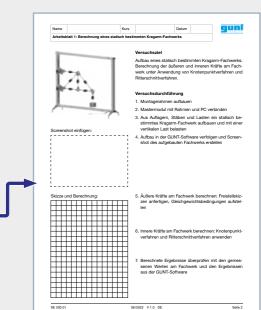




# Digital worksheets

Digital worksheets are available for the individual experiments. Access to solutions is password protected.







# Contact

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